

NAG C Library Function Document

nag_zgbtrs (f07bsc)

1 Purpose

nag_zgbtrs (f07bsc) solves a complex band system of linear equations with multiple right-hand sides, $AX = B$, $A^T X = B$ or $A^H X = B$, where A has been factorized by nag_zgbtrf (f07brc).

2 Specification

```
void nag_zgbtrs (Nag_OrderType order, Nag_TransType trans, Integer n, Integer kl,
                Integer ku, Integer nrhs, const Complex ab[], Integer pdab,
                const Integer ipiv[], Complex b[], Integer pdb, NagError *fail)
```

3 Description

To solve a complex band system of linear equations $AX = B$, $A^T X = B$ or $A^H X = B$, this function must be preceded by a call to nag_zgbtrf (f07brc) which computes the LU factorization of A as $A = PLU$. The solution is computed by forward and backward substitution.

If **trans** = **Nag_NoTrans**, the solution is computed by solving $PLY = B$ and then $UX = Y$.

If **trans** = **Nag_Trans**, the solution is computed by solving $U^T Y = B$ and then $L^T P^T X = Y$.

If **trans** = **Nag_ConjTrans**, the solution is computed by solving $U^H Y = B$ and then $L^H P^T X = Y$.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

- 1: **order** – Nag_OrderType *Input*
On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = **Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.
Constraint: **order** = **Nag_RowMajor** or **Nag_ColMajor**.
- 2: **trans** – Nag_TransType *Input*
On entry: indicates the form of the equations as follows:
 - if **trans** = **Nag_NoTrans**, $AX = B$ is solved for X ;
 - if **trans** = **Nag_Trans**, $A^T X = B$ is solved for X ;
 - if **trans** = **Nag_ConjTrans**, $A^H X = B$ is solved for X .*Constraint:* **trans** = **Nag_NoTrans**, **Nag_Trans** or **Nag_ConjTrans**.
- 3: **n** – Integer *Input*
On entry: n , the order of the matrix A .
Constraint: $n \geq 0$.

- 4: **kl** – Integer *Input*
On entry: k_l , the number of sub-diagonals within the band of A .
Constraint: **kl** ≥ 0 .
- 5: **ku** – Integer *Input*
On entry: k_u , the number of super-diagonals within the band of A .
Constraint: **ku** ≥ 0 .
- 6: **nrhs** – Integer *Input*
On entry: r the number of right-hand sides.
Constraint: **nrhs** ≥ 0 .
- 7: **ab**[*dim*] – const Complex *Input*
Note: the dimension, *dim*, of the array **ab** must be at least $\max(1, \mathbf{pdab} \times \mathbf{n})$.
On entry: the LU factorization of A , as returned by nag_zgbtrf (f07brc).
- 8: **pdab** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix in the array **ab**.
Constraint: **pdab** $\geq 2 \times \mathbf{kl} + \mathbf{ku} + 1$.
- 9: **ipiv**[*dim*] – const Integer *Input*
Note: the dimension, *dim*, of the array **ipiv** must be at least $\max(1, \mathbf{n})$.
On entry: the pivot indices, as returned by nag_zgbtrf (f07brc).
- 10: **b**[*dim*] – Complex *Input/Output*
Note: the dimension, *dim*, of the array **b** must be at least $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when **order** = **Nag_ColMajor** and at least $\max(1, \mathbf{pdb} \times \mathbf{n})$ when **order** = **Nag_RowMajor**.
If **order** = **Nag_ColMajor**, the (i, j) th element of the matrix B is stored in $\mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1]$ and if **order** = **Nag_RowMajor**, the (i, j) th element of the matrix B is stored in $\mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1]$.
On entry: the n by r right-hand side matrix B .
On exit: the n by r solution matrix X .
- 11: **pdb** – Integer *Input*
On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **b**.
Constraints:
if **order** = **Nag_ColMajor**, **pdb** $\geq \max(1, \mathbf{n})$;
if **order** = **Nag_RowMajor**, **pdb** $\geq \max(1, \mathbf{nrhs})$.
- 12: **fail** – NagError * *Output*
The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, **n** = $\langle \text{value} \rangle$.
Constraint: **n** ≥ 0 .

On entry, **kl** = $\langle value \rangle$.

Constraint: **kl** ≥ 0 .

On entry, **ku** = $\langle value \rangle$.

Constraint: **ku** ≥ 0 .

On entry, **nrhs** = $\langle value \rangle$.

Constraint: **nrhs** ≥ 0 .

On entry, **pdab** = $\langle value \rangle$.

Constraint: **pdab** > 0 .

On entry, **pdb** = $\langle value \rangle$.

Constraint: **pdb** > 0 .

NE_INT_2

On entry, **pdb** = $\langle value \rangle$, **n** = $\langle value \rangle$.

Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$, **nrhs** = $\langle value \rangle$.

Constraint: **pdb** $\geq \max(1, \mathbf{nrhs})$.

NE_INT_3

On entry, **pdab** = $\langle value \rangle$, **kl** = $\langle value \rangle$, **ku** = $\langle value \rangle$.

Constraint: **pdab** $\geq 2 \times \mathbf{kl} + \mathbf{ku} + 1$.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter $\langle value \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

For each right-hand side vector b , the computed solution x is the exact solution of a perturbed system of equations $(A + E)x = b$, where

$$|E| \leq c(k)\epsilon|L||U|,$$

$c(k)$ is a modest linear function of $k = k_l + k_u + 1$, and ϵ is the *machine precision*. This assumes $k \ll n$.

If $\hat{x}$ is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_\infty}{\|x\|_\infty} \leq c(k) \text{cond}(A, x)\epsilon$$

where $\text{cond}(A, x) = \| |A^{-1}| |A| |x| \|_\infty / \|x\|_\infty \leq \text{cond}(A) = \| |A^{-1}| |A| \|_\infty \leq \kappa_\infty(A)$. Note that $\text{cond}(A, x)$ can be much smaller than $\text{cond}(A)$, and $\text{cond}(A^H)$ (which is the same as $\text{cond}(A^T)$) can be much larger (or smaller) than $\text{cond}(A)$.

Forward and backward error bounds can be computed by calling `nag_zgbrfs` (f07bvc), and an estimate for $\kappa_\infty(A)$ can be obtained by calling `nag_zgbcon` (f07buc) with **norm** = **Nag_InfNorm**.

8 Further Comments

The total number of real floating-point operations is approximately $8n(2k_l + k_u)r$, assuming $n \gg k_l$ and $n \gg k_u$.

This function may be followed by a call to nag_zgbrfs (f07bvc) to refine the solution and return an error estimate.

The real analogue of this function is nag_dgbtrs (f07bec).

9 Example

To solve the system of equations $AX = B$, where

$$A = \begin{pmatrix} -1.65 + 2.26i & -2.05 - 0.85i & 0.97 - 2.84i & 0.00 + 0.00i \\ 0.00 + 6.30i & -1.48 - 1.75i & -3.99 + 4.01i & 0.59 - 0.48i \\ 0.00 + 0.00i & -0.77 + 2.83i & -1.06 + 1.94i & 3.33 - 1.04i \\ 0.00 + 0.00i & 0.00 + 0.00i & 4.48 - 1.09i & -0.46 - 1.72i \end{pmatrix}$$

and

$$B = \begin{pmatrix} -1.06 + 21.50i & 12.85 + 2.84i \\ -22.72 - 53.90i & -70.22 + 21.57i \\ 28.24 - 38.60i & -20.7 - 31.23i \\ -34.56 + 16.73i & 26.01 + 31.97i \end{pmatrix}.$$

Here A is nonsymmetric and is treated as a band matrix, which must first be factorized by nag_zgbtrf (f07brc).

9.1 Program Text

```
/* nag_zgbtrs (f07bsc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer i, ipiv_len, j, kl, ku, n, nrhs, pdab, pdb;
    Integer exit_status=0;
    NagError fail;
    Nag_OrderType order;

    /* Arrays */
    Complex *ab=0, *b=0;
    Integer *ipiv=0;

#ifdef NAG_COLUMN_MAJOR
#define AB(I,J) ab[(J-1)*pdab + kl + ku + I - J]
#define B(I,J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define AB(I,J) ab[(I-1)*pdab + kl + J - 1]
#define B(I,J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
    Vprintf("f07bsc Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[^\\n] ");
    Vscanf("%ld%ld%ld%ld%*[^\\n] ", &n, &nrhs, &kl, &ku);
```

```

    ipiv_len = n;
    pdab = 2*kl + ku + 1;
#ifdef NAG_COLUMN_MAJOR
    pdb = n;
#else
    pdb = nrhs;
#endif

    /* Allocate memory */
    if ( !(ab = NAG_ALLOC((2*kl+ku+1) * n, Complex)) ||
        !(b = NAG_ALLOC(nrhs * n, Complex)) ||
        !(ipiv = NAG_ALLOC(ipiv_len, Integer)) )
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read A from data file */
    for (i = 1; i <= n; ++i)
    {
        for (j = MAX(i-kl,1); j <= MIN(i+ku,n); ++j)
            Vscanf(" ( %lf , %lf )", &AB(i,j).re, &AB(i,j).im);
    }
    Vscanf("%*[\n] ");
    /* Read B from data file */
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= nrhs; ++j)
            Vscanf(" ( %lf , %lf )", &B(i,j).re, &B(i,j).im);
    }
    Vscanf("%*[\n] ");

    /* Factorize A */
    f07brc(order, n, n, kl, ku, ab, pdab, ipiv, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from f07brc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    /* Compute solution */
    f07bsc(order, Nag_NoTrans, n, kl, ku, nrhs, ab, pdab, ipiv,
        b, pdb, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from f07bsc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    /* Print solution */
    x04dbc(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs, b, pdb,
        Nag_BracketForm, "%.4f", "Solution(s)", Nag_IntegerLabels,
        0, Nag_IntegerLabels, 0, 80, 0, 0, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from x04dbc.\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
}
END:
if (ab) NAG_FREE(ab);
if (b) NAG_FREE(b);
if (ipiv) NAG_FREE(ipiv);
return exit_status;
}

```

9.2 Program Data

f07bsc Example Program Data

```

  4  2  1  2                                     :Values of N, NRHS, KL and KU
(-1.65, 2.26) (-2.05,-0.85) ( 0.97,-2.84)
( 0.00, 6.30) (-1.48,-1.75) (-3.99, 4.01) ( 0.59,-0.48)
              (-0.77, 2.83) (-1.06, 1.94) ( 3.33,-1.04)
              ( 4.48,-1.09) (-0.46,-1.72) :End of matrix A
( -1.06, 21.50) ( 12.85,  2.84)
(-22.72,-53.90) (-70.22, 21.57)
( 28.24,-38.60) (-20.73, -1.23)
(-34.56, 16.73) ( 26.01, 31.97)                :End of matrix B

```

9.3 Program Results

f07bsc Example Program Results

```

Solution(s)
              1              2
1  (-3.0000, 2.0000) ( 1.0000, 6.0000)
2  ( 1.0000,-7.0000) (-7.0000,-4.0000)
3  (-5.0000, 4.0000) ( 3.0000, 5.0000)
4  ( 6.0000,-8.0000) (-8.0000, 2.0000)

```
